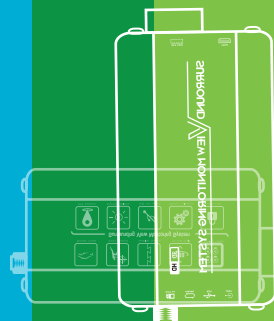


3D HD

Surround View Monitoring System

User's Manual for Buses & Trucks



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Safety Tips



Please read this manual carefully before using and pay attention to this section for the safety Instructions.



Serious traffic accidents may be caused by keeping watching on the screen or operating the system during driving. It is strong recommended that do not operate this system while driving.



SVM is a parking and driving assistant system which offers the road situation around the vehicle to eliminate blind spots and thus works perfectly as a visual guide for safe parking and driving. It may bring inconsistency between the screen image content with actual surroundings of the vehicle. Please handle this case according to actual situation.



Never hotplug the host device when power is connected. The host device can't be sinked in any kind of liquid. Please kindly pay attention to heat dissipation.



Please contact professional installation service providers in case of any abnormal situations.



Brief Introduction

Guide

This guide is to provide the basic illustration for topological structure of the SVM system, operating principle and basic concept to help users to understand the whole system installation procedure, camera calibration steps, and how to interact with the system menu.

Brief Introduction of System

The SVM 3D Around View Monitoring Technology synthesizes images from four cameras to create a true 3D sophisticated view of a vehicle's surroundings. The technology enables flexible omni-directional monitoring around a vehicle from a dynamically definable perspective or "free eye point." Such kind of technology can display the complete vision of the positioning and moving path of the vehicle, it covers blind spot and thus works perfectly as a safe parking and driving guide even when restricted by adjacent vehicles and objects, parking line, etc. The system offers various SVM system configurations like -HDMI/LVDS/AV with alternative version of 2D or 3D, and what's more, this system also integrated four channel car DVR function with 24 hours videos loop recording supported.



Product Features

Product Features

Four 180 degrees ultra wide fish-eye cameras

Seamless video merging based on dual core ARM CPU and hardware high efficiency acceleration engine.

Arbitrary and dynamic 3D mode view angle switching for better surrounding environment observation

Independent Fish-eye calibration parameter and algorithm for each camera.

Pixel statistic engine for realtime brightness balance among four channels outside cameras.

3D video de-interlacing and noise reduction technology for CVBS signal decoding.

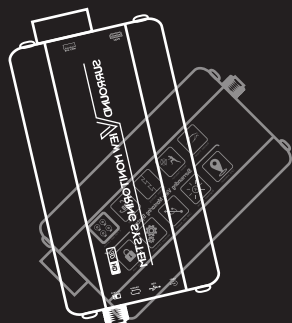
Support alternative recording media for TF card or USB disk

The simplest calibration steps with calibration tape and packing box, and system applicable for almost all types of vehicle including Buses, Trucks, Lorries, Limousines, Tanks and even Jumbo Jets. Typical length of the vehicle is 5.5m, 6.5m, 10m & 13m.

Smart power managements to save automobile's battery

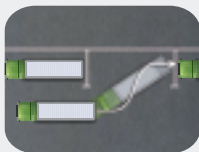
High video recording resolution up to 1440*960.

OE quality for main chipset with well protected circuit and devices in order to achieve the best system performance and stability.



Product Features

Main application scenarios



Side Parking



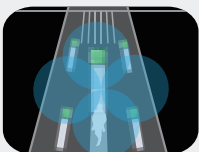
Reverse Parking



Narrow Road/Lane



Slope sections



Blind Spots Coverage



Turning assist



Security&Surveillance



Car DVR



Crowded Road

Features Profile

3D & 360° Seamless Merging

360° Blind Spots Coverage

Dynamic & Intelligent View Angle Switching

Flexible Omni-directional Monitoring

Exclusive Fish-eye Distortion Correction

Guided Camera Calibration

Driving Video Recording

G-sensor Triggered Recording

Optional Function

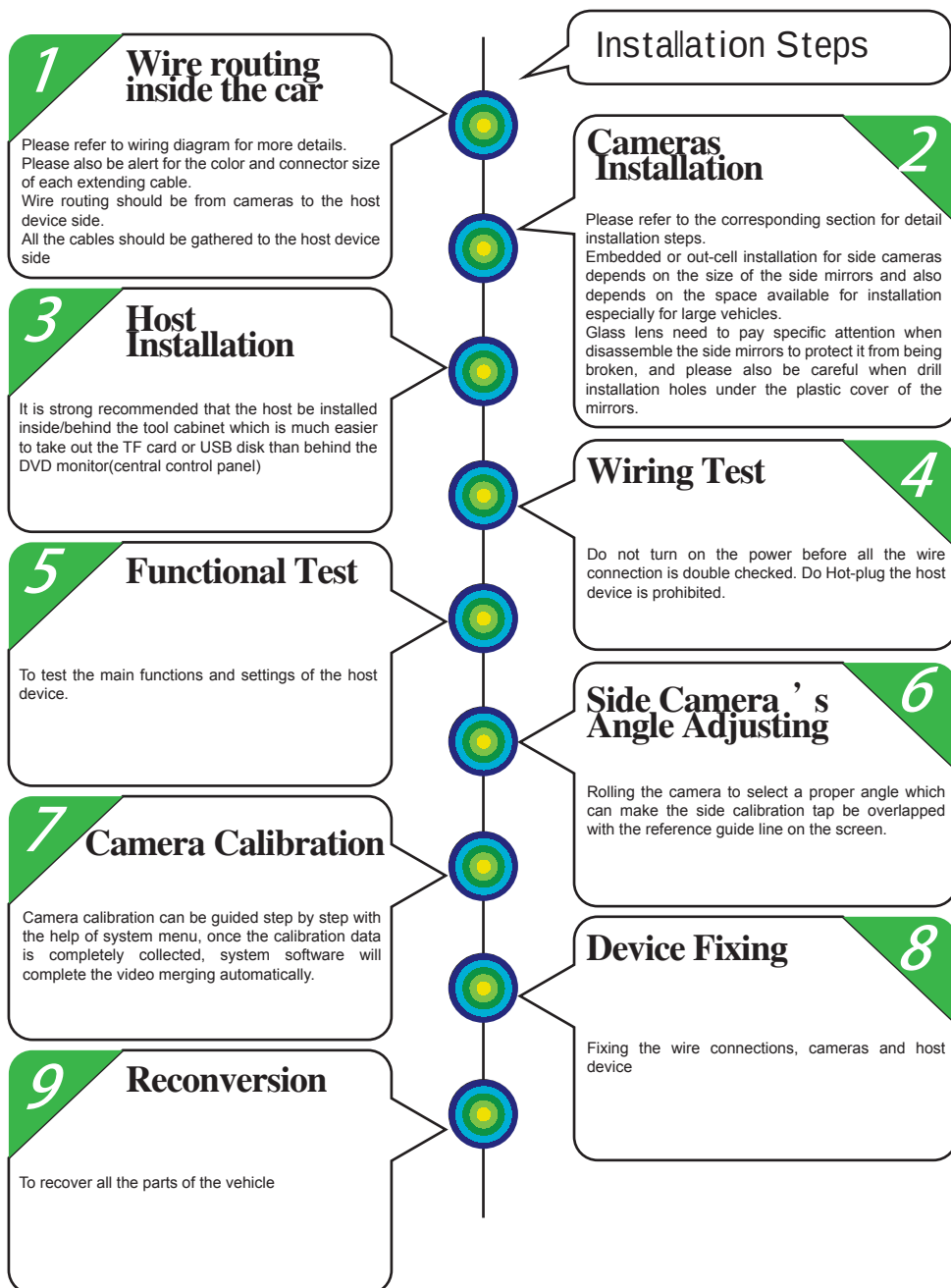
a.24 Hour Parking Monitoring

b.Visual Radar Extension

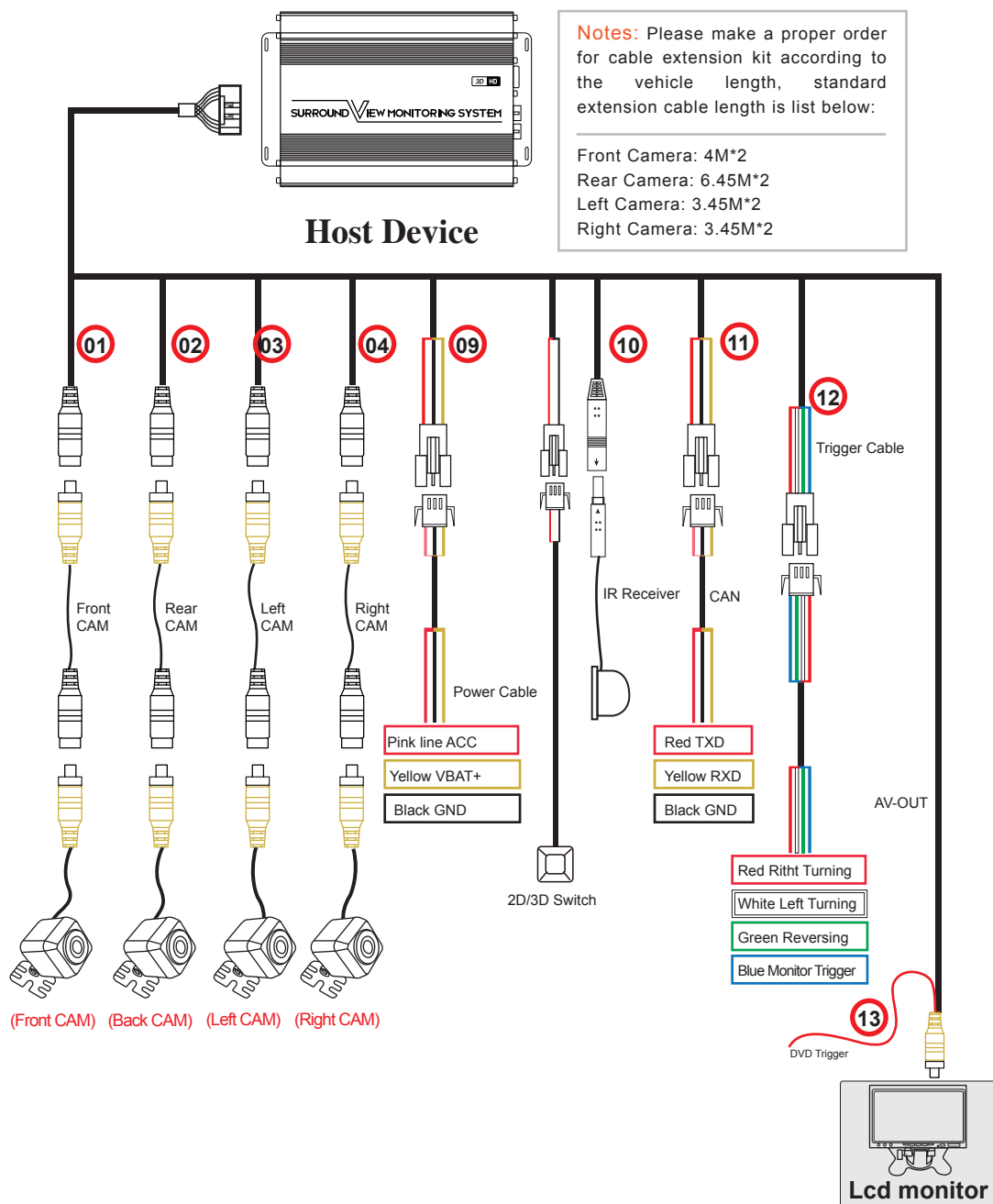
Note:

This manual gives a basic and general feature description of the system, but it may vary from specific product model and application case. Please consult sales team for detail specifications before ordering.

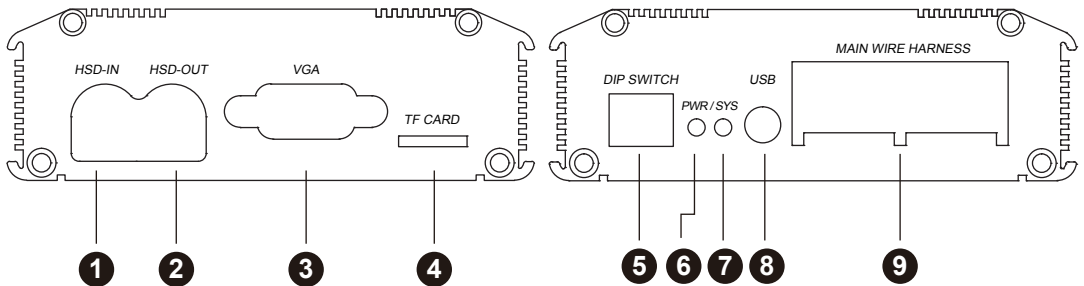
System Hardware Installation



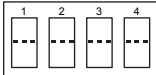
Wiring Diagram



Product Overview



OFF = 1



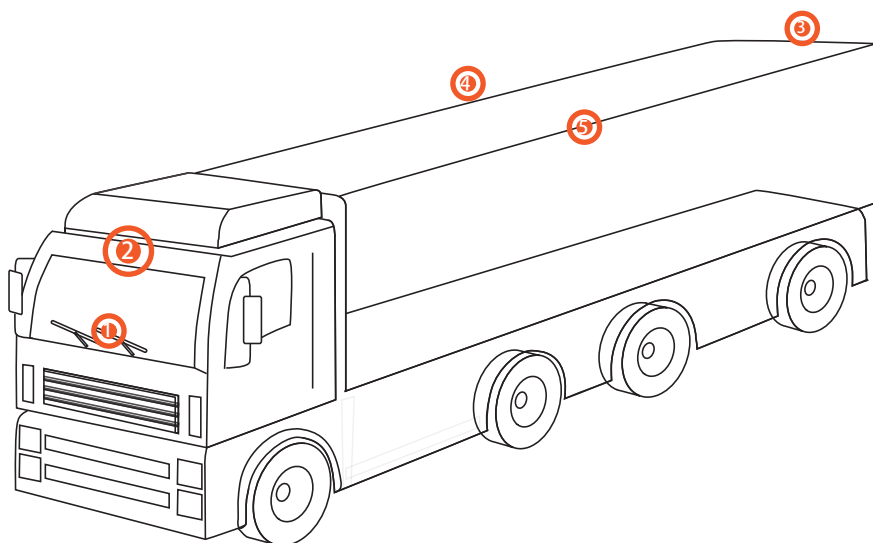
ON = 0

DIP SWITCH		EXAMPLE	
[1]	AV / AHD selection OFF = AV ON = AHD	[1]	AHD - PAL (720p30) 0 1 1 1 AHD - NTSC (720p25) 0 1 0 1
[2]	Enhanced / standard CVBS quality OFF = Enhanced CVBS Quality ON = Standard CVBS Quality		
[3]	NTSC / PAL selection OFF = NTSC ON = PAL	[2]	Enhanced CVBS - NTSC 1 1 1 1 Enhanced CVBS - PAL 1 1 0 1
[4]	Standard / High framerate OFF = Standard frame rate ON = High frame rate (Extra upgrading procedure required!!!)		
		[3]	High frame rate AHD - NTSC 0 1 1 0 High frame rate AHD - PAL 0 1 0 0

Number	Port Name	Port Description
[1]	HSD-IN	High Speed LVDS Data Input
[2]	HSD-OUT	High Speed LVDS Data Output/Loopback
[3]	VGA	VGA Video Out
[4]	TF CARD	microTF Card Slot
[5]	DIP SWITCH	Interface DIP Switch
[6]	PWR	Power Status Indicator
[7]	SYS	System Status Indicator
[8]	USB	Slot for Recording Video Storage
[9]	MAIN WIRE HARNESS	Integrate Wire Harness Socket

Cameras Location For Trucks

Perspective Drawing



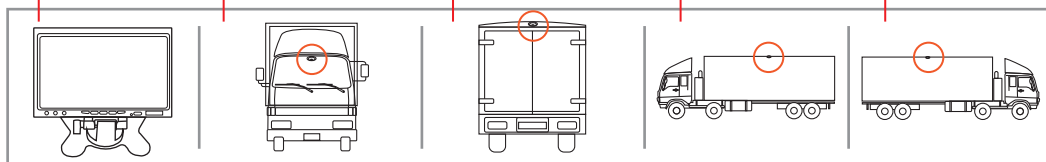
① Lcd Monitor

② Front Camera

③ Rear Camera

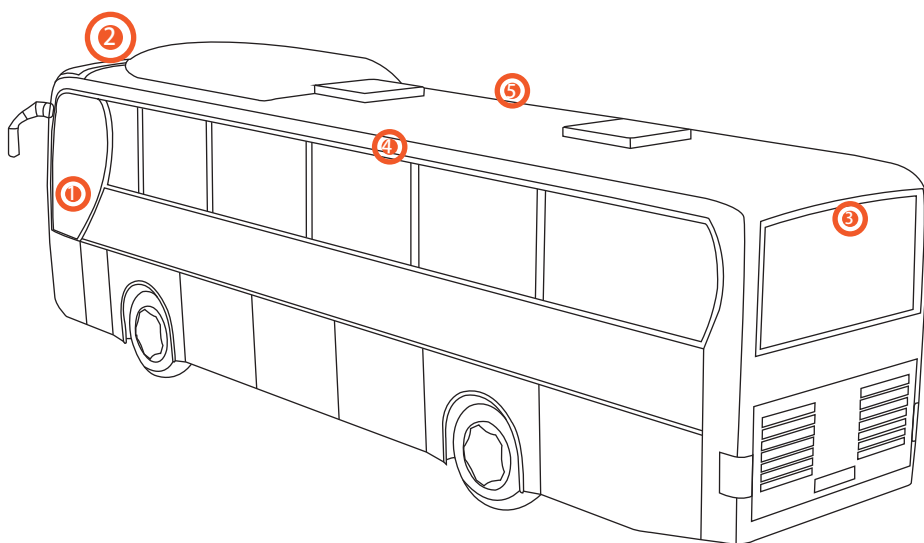
④ Left Camera

⑤ Right Camera



Cameras Location For Buses

Perspective Drawing



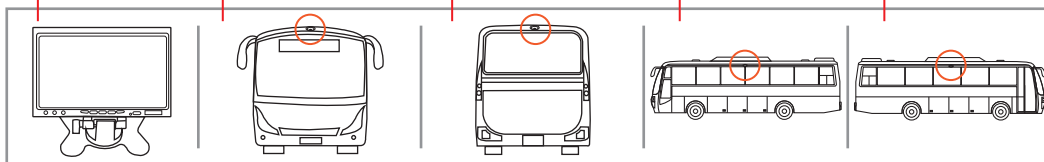
① Lcd Monitor

② Front Camera

③ Rear Camera

④ Left Camera

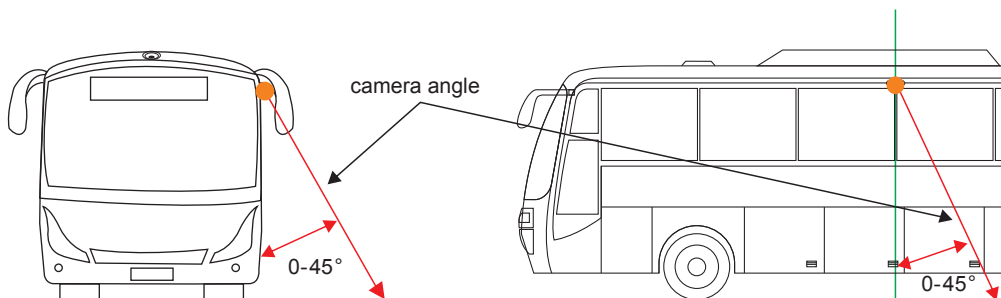
⑤ Right Camera



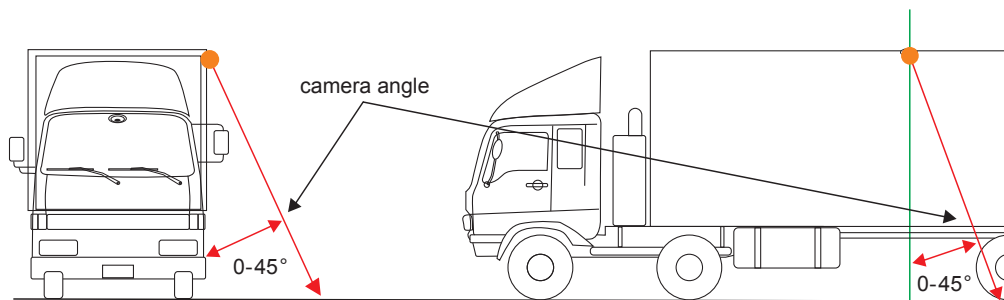
Cameras Installation Angle For Buses/Trucks

Please keep in mind that choosing a proper camera installation position to get as many pixel contents as possible while keeping the body of the vehicle visible. The camera optical axis should keep a vertical angle of 45 degree appropriately corresponding to vehicle body. For buses and trucks camera installation, it is strong recommended to install all the cameras in the middle point of each top side which illustrated as follows:

Camera Installation Angle For Buses

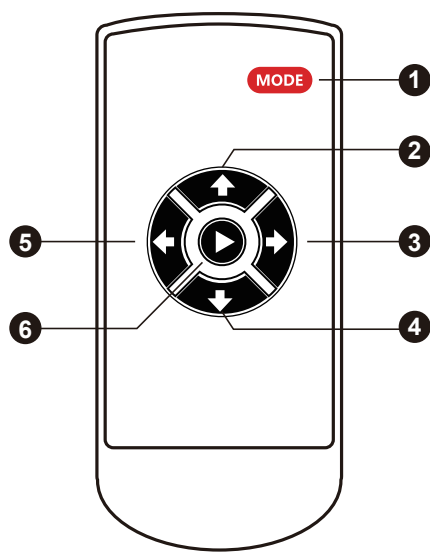


Camera Installation angle For Trucks



Remote Controller Introduction

Perspective Drawing



Key Number	Description	Function
[1]	MODE	Enter Setting Menu
		In 3D Mode, long press 2 seconds enter into 4CH recording mode
[2]	UP	While in MENU screen, toggle through the icons
		In SVM Mode, short press enter high beam mode, press again back to SVM mode
[3]	RIGHT	In SVM model, long press enter into right 360 rotatable mode
[4]	DOWN	In SVM mode, long press enter into reversing gear mode
		In menu setting, select next menu option
[5]	LEFT	In SVM model, long press enter into 360 rotateable mode
[6]	Confirm	Confirm selected option

Host Device Installation

Host Device Installation Steps

1. Disassemble the panel of central control unit, and connect the reversing video channel of Lcd monitor or other display screen(AV in).

2. The host control unit installation:

IR Mode: Put the infrared receiver in a proper position.

3. Please connect the anode of the left/right turning signal from the fuse box to host wire harness, or from side mirror turning LED indicator to the camera side of the extending cable.

4. Connect the power cable to batter supplier line and connect the wire harness to the host device..

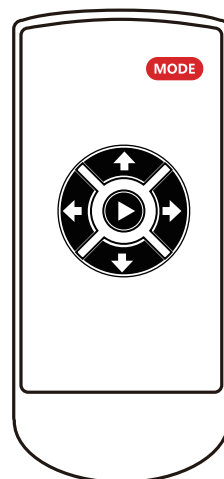
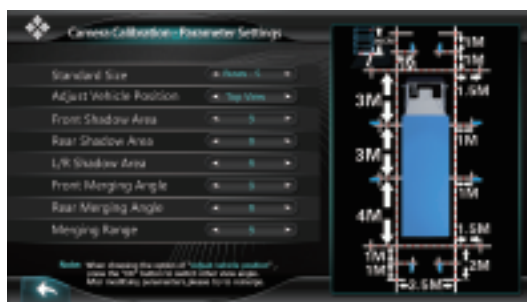
5. Fix the host device in the tool cabinet or the space behind the central control panel.

6. Connect all the cables for the coming function testing and debugging procedure, and assemble the panel back to the control unit.



Camera Calibration

Calibration Parameters Setting

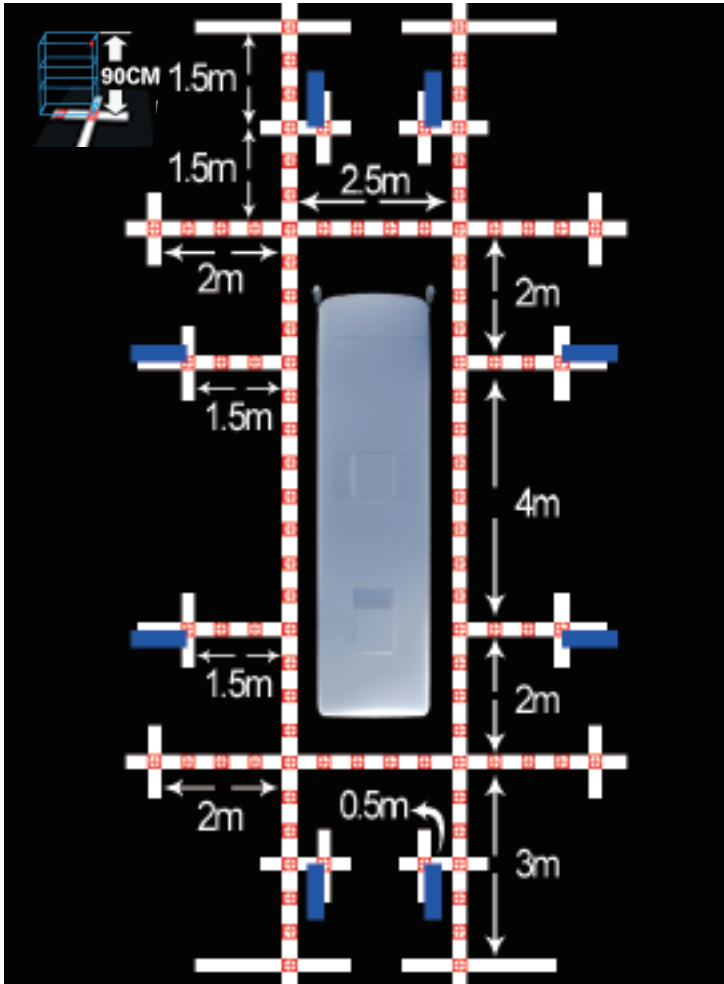


First of all, please short press the "MODE" button on the remote controller enter system menu settings.

Second, please select the correct calibration size for the applied vehicle model, set the shadow area and each step of the shadow setting is 5cm, please keep it as the default if you are not sure with the sensor type.

Camera Calibration For Buses - S

Calibration Tape Sticking



Note:

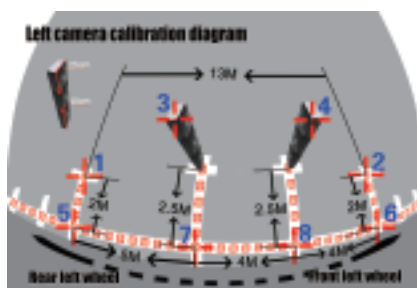
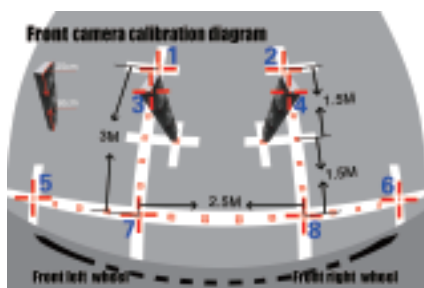
As the menu diagram shows, pasting the calibration tape around the vehicle.

Please refer to the calibration pictures of different vehicle models and sizes to select the correct one for matching your vehicle.

Camera Calibration For Buses - S

Calibration Points Marking

You can start calibrating the four cameras one by one when the cursor is twinkling. Moving the cursor to the corresponding locations by the remote controller buttons of up/down/left/right, then press the “ok” button to mark the current calibration point in the screen and then the system menu will guide you to the next calibration pixel point in order from 1 to 8 one by one, please see the correct location and sequence of the calibration points as below pictures:



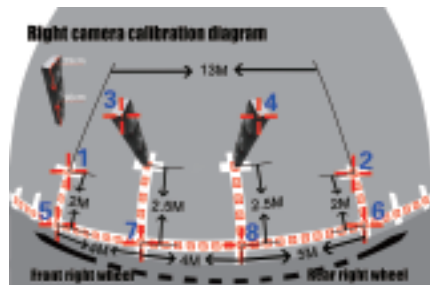
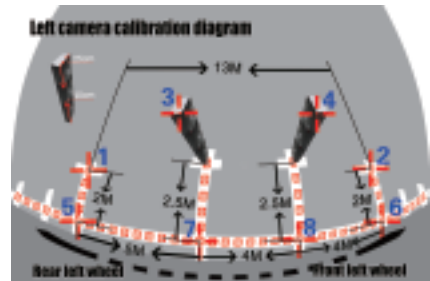
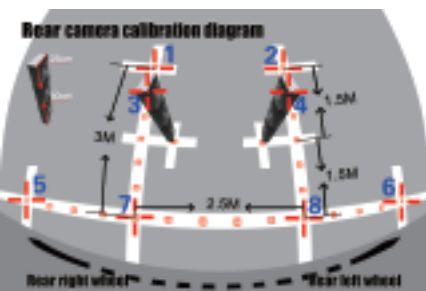
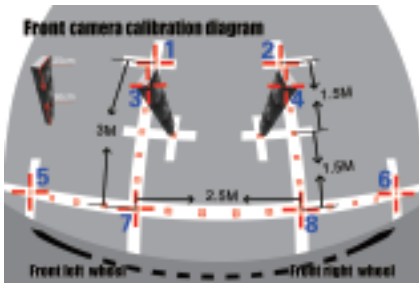
Press the red “Mode” button to toggle to previous calibration point selection when needed.

Notes: The calibration locations of No.7 calibration pixel point and No.8 calibration pixel point between the front&rear cameras and the sides cameras are totally different. The more accurate calibration points you mark, the better quality of the panoramic image merging will be.

Camera Calibration For Buses - S

Placing Packing Box

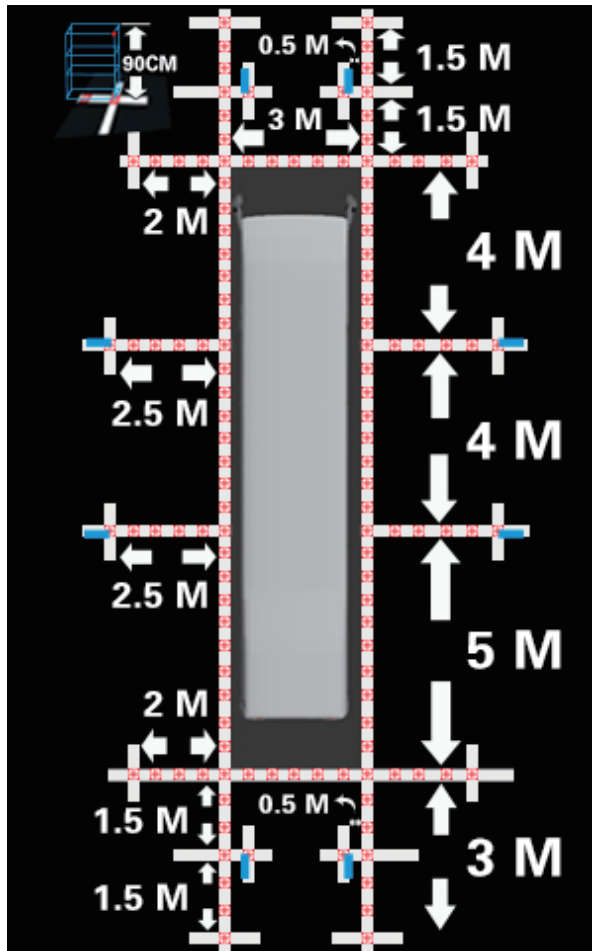
There are always 8 calibration points for each camera which need to be marked in the screen, the third pixel point and forth calibration point are always special points which are actually the diagonal corner of the packing box. The packing boxes can be divided into outer and inner one so that each packing box can be used for calibration 1 camera each time.



Notes: Put the 3 packing boxes in the correct position separately as the pictures above illustrated. You can also use other boxes instead as a calibration reference objects, the dimension requirements of the box must be 90cm in height.

Camera Calibration For Buses - M

Calibration Tape Sticking



Note:

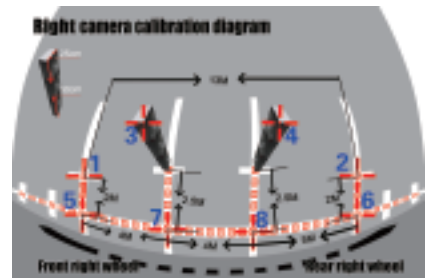
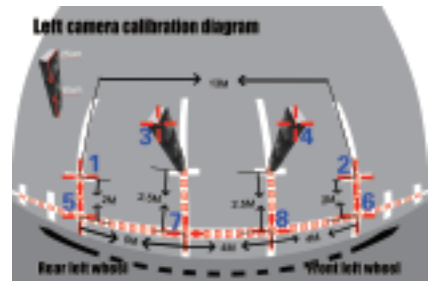
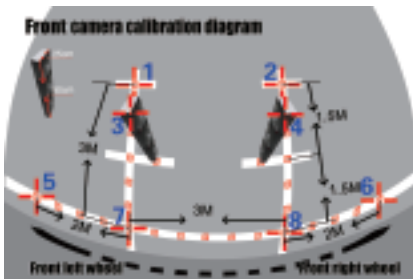
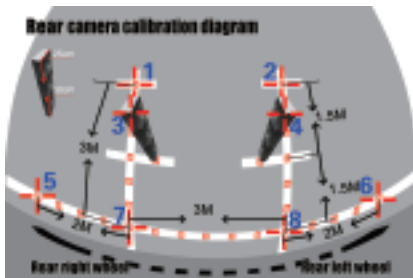
As the menu diagram shows, pasting the calibration tape around the vehicle.

Please refer to the calibration pictures of different vehicle models and sizes to select the correct one for matching your vehicle.

Camera Calibration For Buses - M

Placing Packing Box

There are always 8 calibration points for each camera which need to be marked in the screen, the third pixel point and fourth calibration point are always special points which are actually the diagonal corner of the packing box. The packing boxes can be divided into outer and inner one so that each packing box can be used for calibration 1 camera each time.

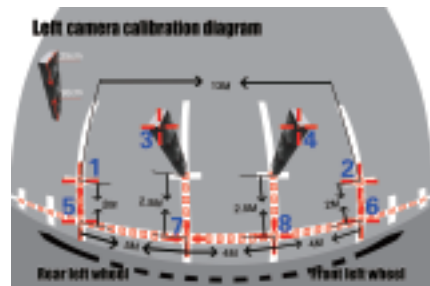
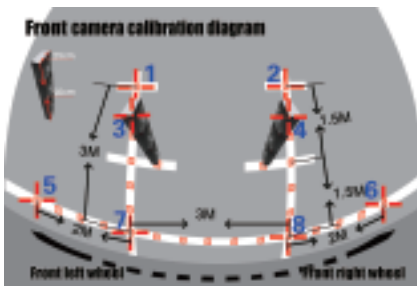


Notes: Put the 3 packing boxes in the correct position separately as the pictures above illustrated. You can also use other boxes instead as a calibration reference objects, the dimension requirements of the box must be 90cm in height.

Camera Calibration For Buses - M

Calibration Points Marking

You can start calibrating the four cameras one by one when the cursor is twinkling. Moving the cursor to the corresponding locations by the remote controller buttons of up/down/left/right, then press the “ok” button to mark the current calibration point in the screen and then the system menu will guide you to the next calibration pixel point in order from 1 to 8 one by one, please see the correct location and sequence of the calibration points as below pictures:

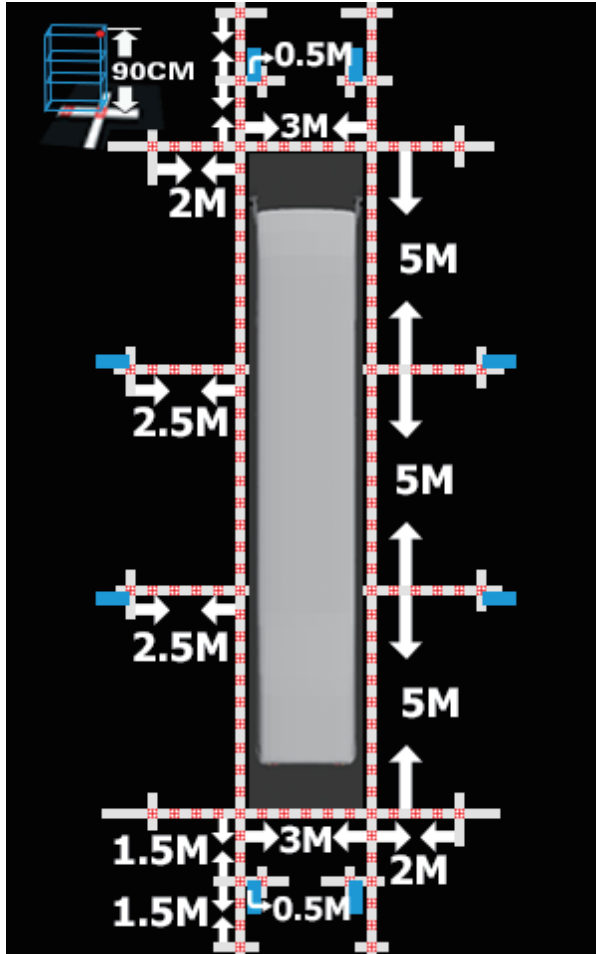


Press the red “Mode” button to toggle to previous calibration point selection when needed.

Notes: The calibration locations of No.7 calibration pixel point and No.8 calibration pixel point between the front&rear cameras and the sides cameras are totally different. The more accurate calibration points you mark, the better quality of the panoramic image merging will be.

Camera Calibration For Buses - L

Calibration Tape Sticking



Note:

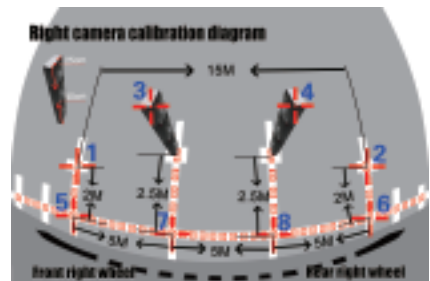
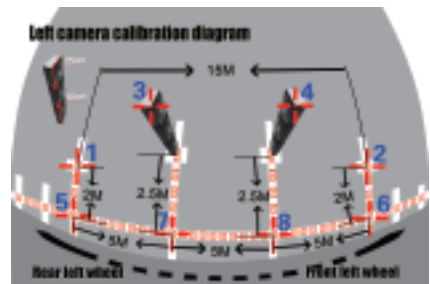
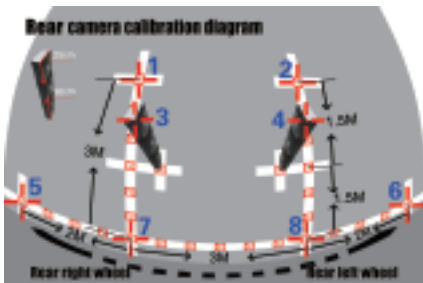
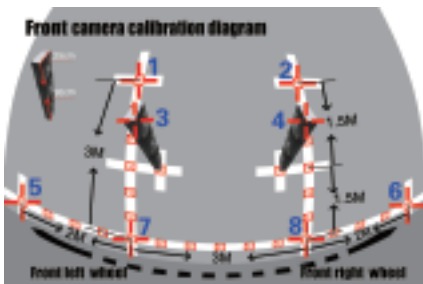
As the menu diagram shows, pasting the calibration tape around the vehicle.

Please refer to the calibration pictures of different vehicle models and sizes to select the correct one for matching your vehicle.

Camera Calibration For Buses - L

Placing Packing Box

There are always 8 calibration points for each camera which need to be marked in the screen, the third pixel point and forth calibration point are always special points which are actually the diagonal corner of the packing box. The packing boxes can be divided into outer and inner one so that each packing box can be used for calibration 1 camera each time.

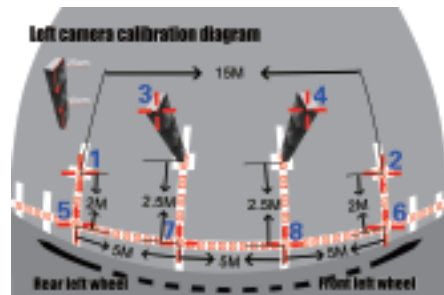
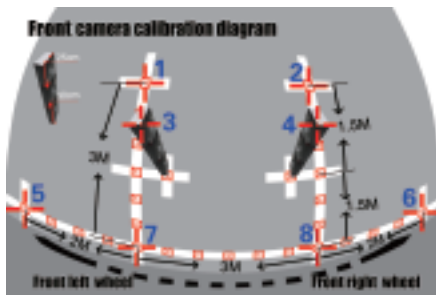


Notes: Put the 3 packing boxes in the correct position separately as the pictures above illustrated. You can also use other boxes instead as a calibration reference objects, the dimension requirements of the box must be 90cm in height.

Camera Calibration For Buses - L

Calibration Points Marking

You can start calibrating the four cameras one by one when the cursor is twinkling. Moving the cursor to the corresponding locations by the remote controller buttons of up/down/left/right, then press the “ok” button to mark the current calibration point in the screen and then the system menu will guide you to the next calibration pixel point in order from 1 to 8 one by one, please see the correct location and sequence of the calibration points as bellow pictures:

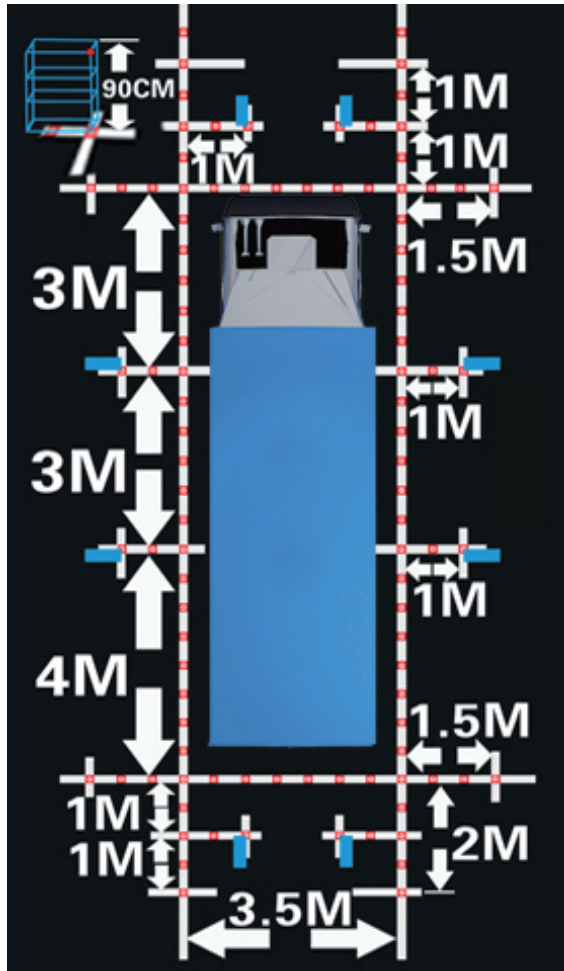


Press the red “Mode” button to toggle to previous calibration point selection when needed.

Notes: The calibration locations of No.7 calibration pixel point and No.8 calibration pixel point between the front&rear cameras and the sides cameras are totally different. The more accurate calibration points you mark, the better quality of the panoramic image merging will be.

Camera Calibration For Trucks

Calibration Tape Sticking



Note:

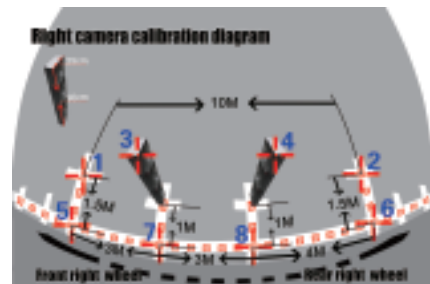
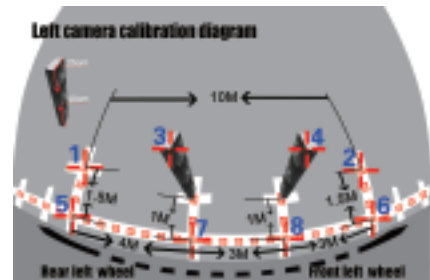
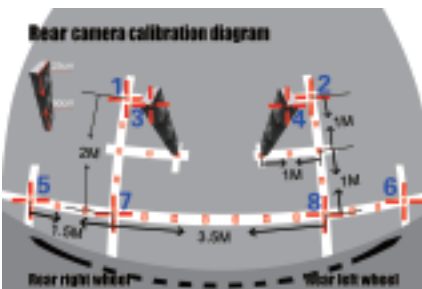
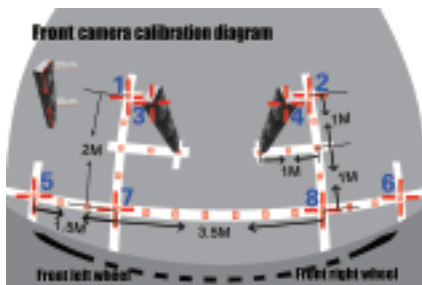
As the menu diagram shows, pasting the calibration tape around the vehicle.

Please refer to the calibration pictures of different vehicle models and sizes to select the correct one for matching your vehicle.

Camera Calibration For Trucks

Placing Packing Box

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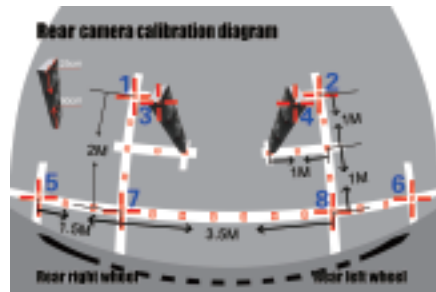
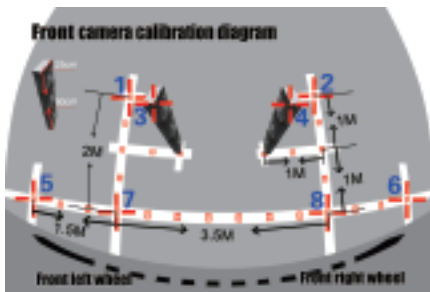


Notes: Put the 3 packing boxes in the correct position separately as the pictures above illustrated. You can also use other boxes instead as a calibration reference objects, the dimension requirements of the box must be 90cm in height.

Camera Calibration For Trucks

Calibration Points Marking

You can start calibrating the four cameras one by one when the cursor is twinkling. Moving the cursor to the corresponding locations by the remote controller buttons of up/down/left/right, then press the “ok” button to mark the current calibration point in the screen and then the system menu will guide you to the next calibration pixel point in order from 1 to 8 one by one, please see the correct location and sequence of the calibration points as below pictures:



Press the red “Mode” button to toggle to previous calibration point selection when needed.

Notes: The calibration locations of No.7 calibration pixel point and No.8 calibration pixel point between the front&rear cameras and the sides cameras are totally different. The more accurate calibration points you mark, the better quality of the panoramic image merging will be.

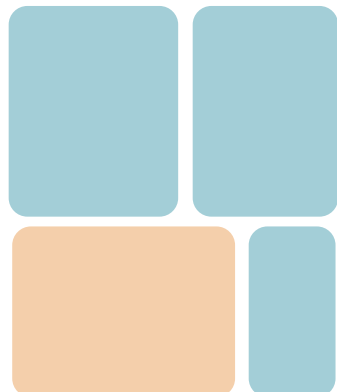


Camera Calibration

Merging Calculation



Press "OK" to start image merging. Do not shut down during this operation, System will reboot automatically after image merging finished.



User Settings



3D Full Screen Display Mode

Full Screen



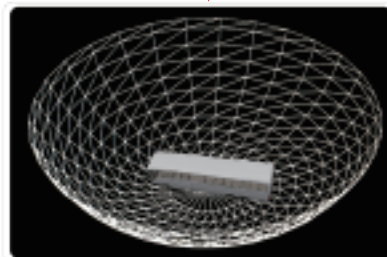
Default view



Reversing view

Right view
(Turning signal)

Left view
(Turning signal)



Function Settings

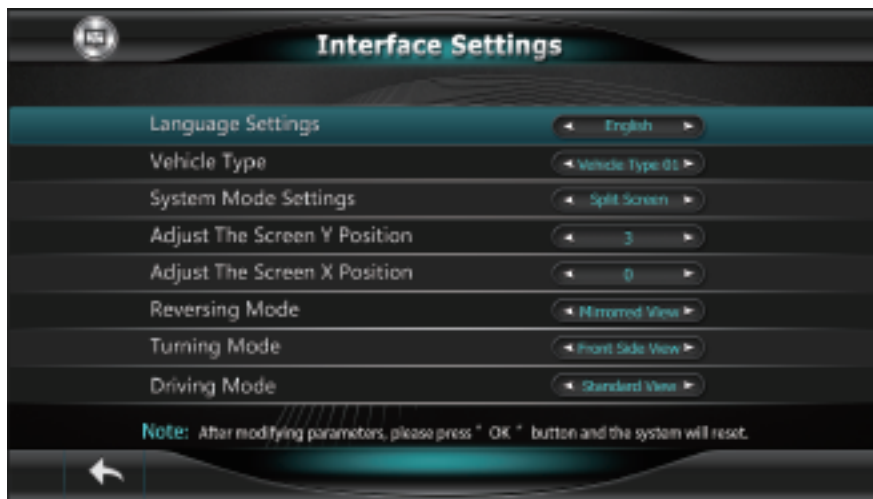
Parameters Setting and Menu Description



Menu Item	List Options	Description
Turn Signal Wakeup	ON / OFF	Turning Signal is optional after engine is fired, this option is a global switch for left and right turning indicator, when this option is set to ON, when the turning event is triggered, the SVM system will response to this event, and vice, versa.
Activate Turn Signal	ON / OFF	When the SVM is going to standby mode, this option is use to control whether the SVM system can be activated through turning signals.
Emergency Blinker Wakeup	ON / OFF	When the SVM is going to standby mode, this option is use to control whether the SVM system can be activated from Emergency Blinker, and you can also use Emergency Blinker to set it back to standby mode again when this option is set to ON.
High Beam Function	ON / OFF	Just like the turning signal, high beam signal is useful to toggle the free-eye point and change the view angle for surround safety.
3D Dynamic Angle Function	ON / OFF	Set static or dynamic angle switching whe response to trigger event.
Top View	ON / OFF	
Virtual Wing Mirror	ON / OFF	
Side CAM PIP	ON / OFF	



Interface Settings



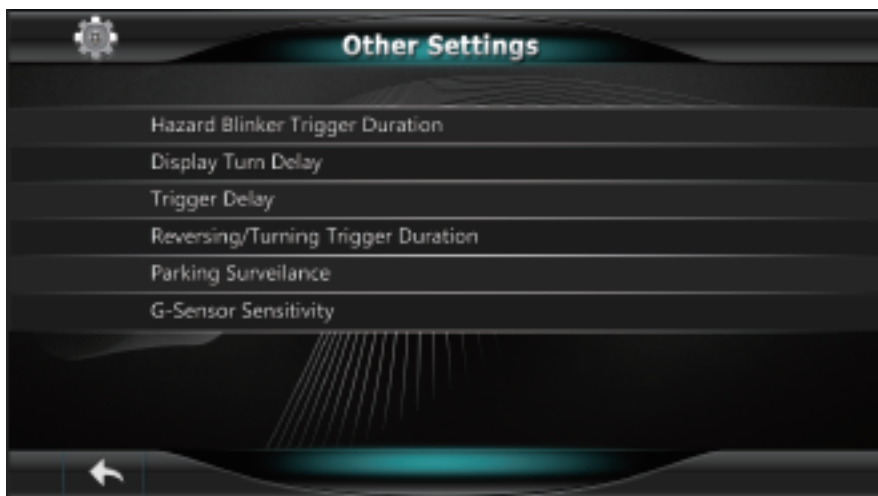
Menu Item	List Options	Description
Language Setting	English/ Simplified Chinese	Set different user interface language.
Vehicle Brand Setting	Vehicle Type 1...3	Set 3D car model.
System Mode Setting	Full Screen	Set fullscreen / split screen for different view mode.
Adjust The Screen Y Position	-9 ~ +9 Pixel	Screen TCON horizontal front porch and back porch control.
Adjust The Screen X Position	-9 ~ +9 Pixel	Screen TCON vertical front porch and back porch control.
Reversing Mode	Mirrored View	Set different view angle when reversing
Turning Mode	Front Side View	Set different view angle when turning
Driving Mode	Standard View	Set different view angle when driving

Upgrade & Restore



Menu Item	List Options	Description
System Restore	Default/ User Preference	Default is not functional at this moments, and choose user preference to restore user preference of video settings/window configurations etc.
Upgrade Options	Upgrade 3D Mode	Using thes menu for manipulating with UI / Celibration data / Apps.
Version Information	SW.6030.R2.14	Check hardware / Firmware / software version.

Other Settings



Menu Item	List Options	Description
Hazard Blinker Trigger Duration	1Min/3Min/5Min/ 3S/5S/30S/	Since the system can be activated through external Emergency Blinker, you can also set the duration time, but do remember to turn ON the Emergency Blinker Activation function first in Function Settings Menu.
Display Turn Delay	30S/1Min/ 3Min/5Min/	Option is used for setting the delay for generated reversing indication signal to inform multimedia monitor that the input video is ready.
Trigger Delay	30S/1Min/ 3Min/5Min/	This option is used to set the whole latency to response the release event of turning signal.
Reversing / Turning Trigger Duration	30S/1Min/ 3Min/5Min/	Set the "ON" duration for monitor after waked up by reversing / turning signal.
Parking Surveillance	Disable	Set different surveillance mode after parking.
G-Sensor Sensitivity	Middle/High/Low	



Video Settings

Menu Item	List Options	Description
Saturation	-9 ~ +9	Adjust input video saturation
Brightness	-9 ~ +9	Adjust input video brightness
Contrast	-9 ~ +9	Adjust input video contrast
Sharpness	-9 ~ +9	Adjust input video sharpness



Video Recording Functions

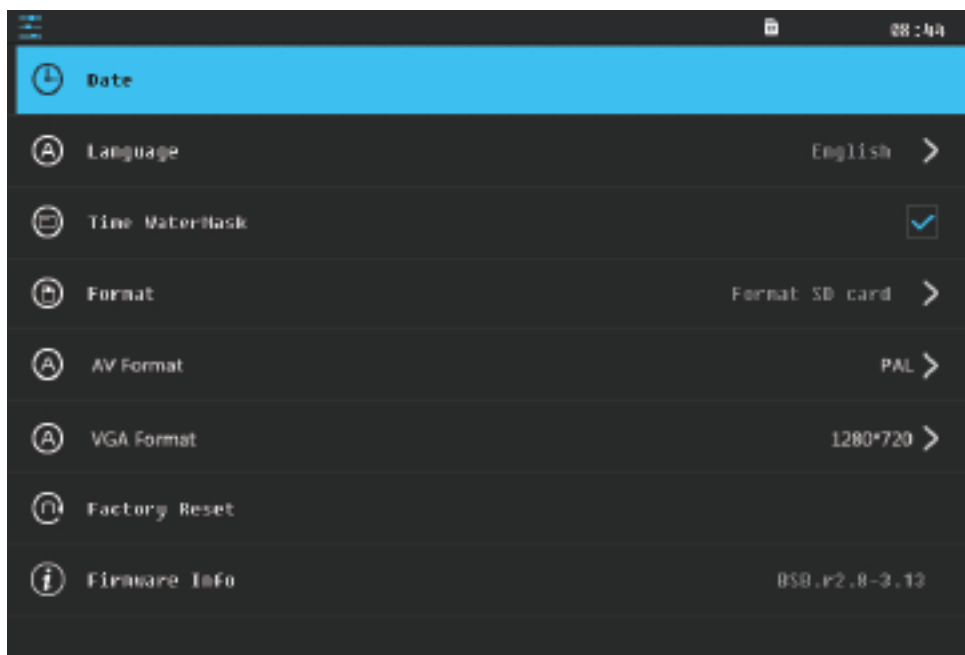
1. Long press “Mode” button to switch to recording system menu.
2. Press the “OK” button to stop current recording.
3. Using “Up/Down” button to navigate between recorded files as per date and timeline.
4. Press “OK” button again if the current recording file is just the right one you want to playback, and you can enlarge any of the 4 cameras to full screen mode by pressing left /right/up/down Button.



Recording Menu



Basic Settings

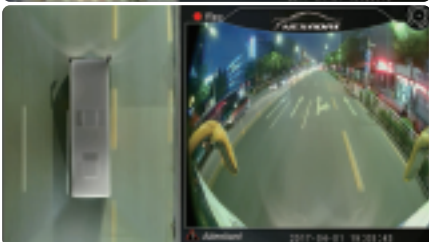


Menu Item	List Options	Description
Date		Change system time
Language	English/Chinese	
Time Watermark	ON/OFF	
Format		Format the TF Card or USB Disk
Factory Reset		
Firmware Info		



3D Dynamic View Display Mode

More Example



Packing List



Packing List



Host



Front Camera



Rear Camera



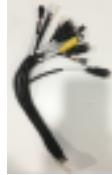
Left Camera



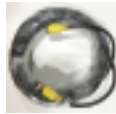
Right Camera



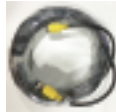
Remote Controller



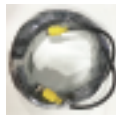
Main Wire Harness



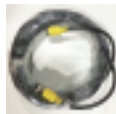
Front Extend Cable



Rear Extend Cable



Left Extend Cable



Right Extend Cable



IR Receiver

Note:

The configuration may generate differences due to different vehicle size or product model



Calibration Tape

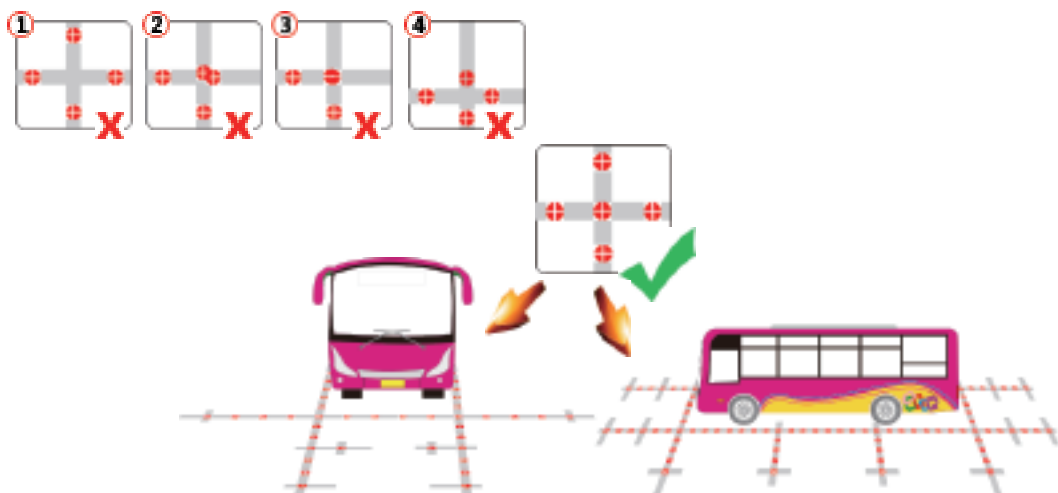


Specification

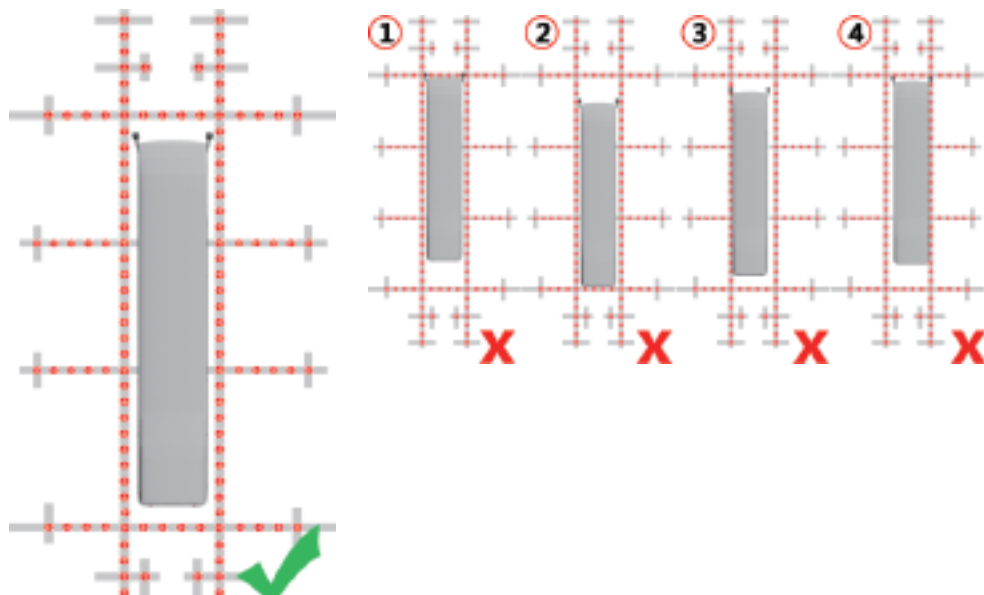
Datasheet

Type	Specification	
Video	Video Interface	Mini plug connector
	Input / Output Impedance	75Ω AHD
	Amplitude	Typical 1Vpp, 1.2Vpp Maximum
	Bandwidth	27MHz
	Sampling Frequency	74.25MHz
	DP(Differential Phase)	<0.8° TYP
	DG(Differential Gain)	<3%TYP
	SNR	70dB
Indicator Lamp /Blinker	High beam	Optional
	Left/Right Turning Blinker	Yes
	Reversing Lamp	Yes
G-sensor	BM250E	Bosch
Compression	Algorithm	H.264 Baseline@L3.1
	Resolution	1920*1080@15fps
	Bitrates	5Mbps, 3Gbyte/Hour
	Recording Media	USB Disk(High Priority)/TF
Disk Capacity	TF CARD	32G SDIO3.0/SDIO2.0
	USB Disk	256G USB2.0
Power Consumption	4-CH DVR + SVM mode	550mA
	4-CH DVR mode	550mA
	Sleep Mode	<10mA
Dimension	L*W*H	134*100*30mm(Host Metal box)
Weight		220g
Environments	Normal Working	-20℃~+85℃
	Storage	-40℃~+105℃
	Relative Humidity	0~95%
Voltage Tolerance	Working Voltage	9.5V~36V

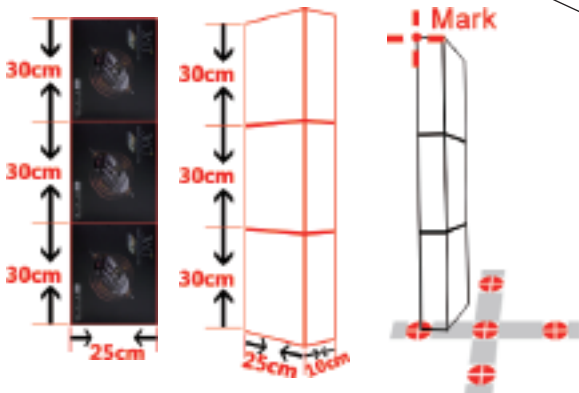
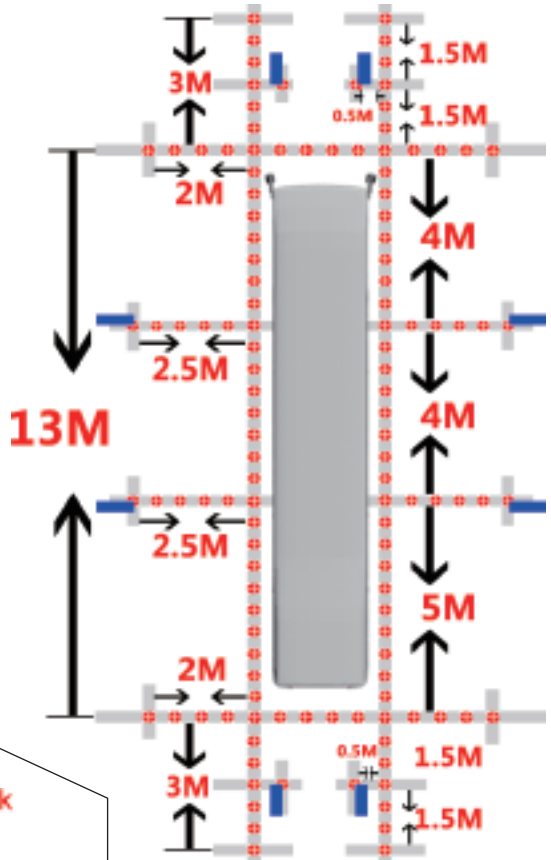
Paste the calibration tape **Trouble 1**



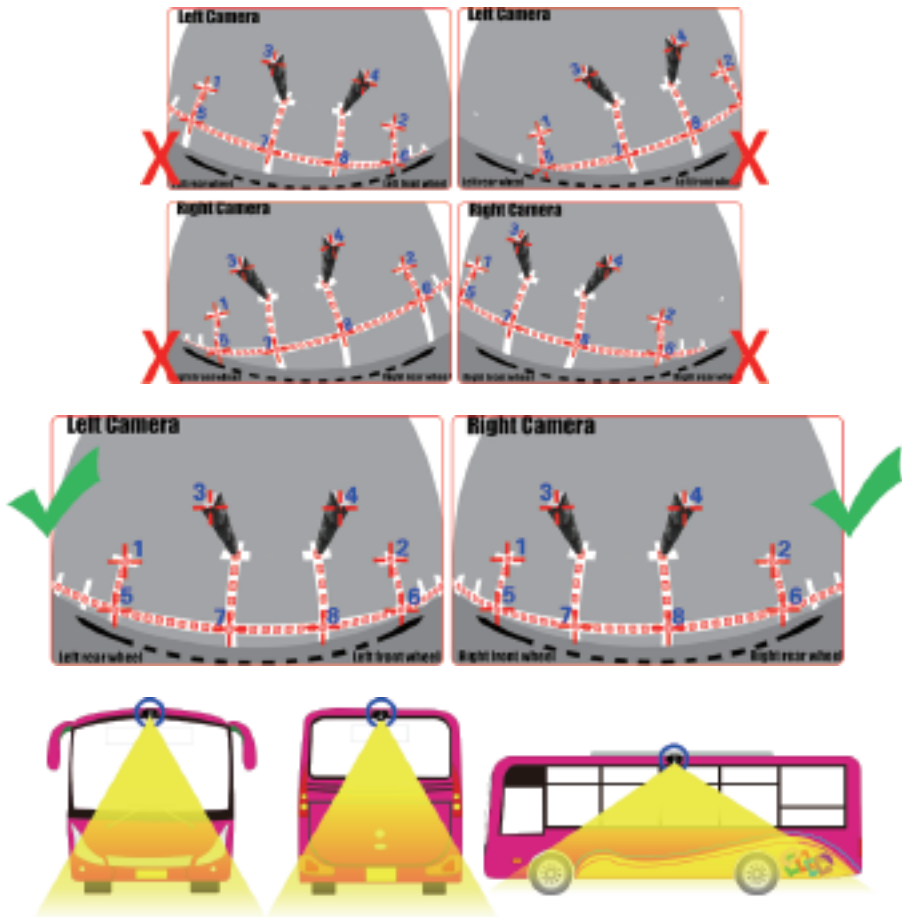
Vehicle parking **Trouble 2**



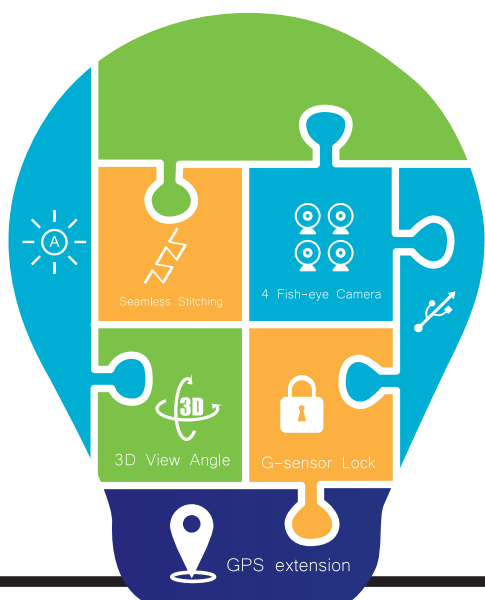
Trouble 3 Put the gift boxes



Adjusting camera angle & Mark calibration points Trouble 4



The camera axis should keep a vertical angle of 45° appropriately with vehicle body. with the help of guided preview window provided in system software menu, please keep in mind to keep the whole calibration tape and all 8 calibration points visible while keep as many pixel as possible.



Surround View Monitoring System



Service Promise



As a leading R&D enterprise in the Automobile industry, we are committed to engineering and manufacturing our products to the highest standards of quality, performance, and value. From our advanced product design, manufacturing and quality control procedures to our friendly and knowledgeable support teams, our commitment to satisfy you is paramount. In every interaction with us, you can be confident you will receive our commitment to Service, Support, and Solutions. For 7 years, our objective has been to ensure that every customer is completely satisfied with every purchase. To underscore this commitment, we offer our Satisfaction Guarantee. This means we will work diligently to resolve any issue you have with your purchase until you are completely satisfied. Our employees are prepared to do whatever it takes to make certain that the entire process of doing business with us is a positive and professionally rewarding experience for you. We greatly appreciate your business. It is our intent to keep you as a customer for life.

